# New Exact Solutions of Nonlinear Partial Differential Equations Using Tan-Cot Function Method 

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> Abstract: In this paper, we established a traveling wave solution by using the proposed Tan-Cot function algorithm for nonlinear partial differential equations. The method is used to obtain new solitary wave solutions for various type of nonlinear partial differential equations such as, the $(2+1)$ - dimensional nonlinear Schrödinger equation, Gardner equation, the modified KdV equation, perturbed Burgers equation, general Burger's-Fisher equation, and Benjamin-Bona-Mahony equation, which are the important Soliton equations. Proposed method has been successfully implemented to establish new solitary wave solutions for the nonlinear PDEs.

Key words: Nonlinear PDEs; Exact solutions; Tan-cot function method; Schrödinger equation; Gardner equation; The modified KdV equation; Perturbed Burgers equation; General Burger's-Fisher equation; Benjamin-Bona-Mahony equation

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## 1. INTRODUCTION

Large varieties of physical, chemical, and biological phenomena are governed by nonlinear partial differential equations. One of the most exciting advances of
nonlinear science and theoretical physics has been the development of methods to look for exact solutions of nonlinear partial differential equations [1]. Exact solutions to nonlinear partial differential equations play an important role in nonlinear science, especially in nonlinear physical science since they can provide much physical information and more insight into the physical aspects of the problem and thus lead to further applications. Nonlinear wave phenomena of dispersion, dissipation, diffusion, reaction and convection are very important in nonlinear wave equations. In recent years, quite a few methods for obtaining explicit traveling and solitary wave solutions of nonlinear evolution equations have been proposed. A variety of powerful methods, such as, tanh-sech method [2-4], extended tanh method [5-7], hyperbolic function method [8,9], Jacobi elliptic function expansion method [10], F-expansion method [11], and the First Integral method [12,13]. The sine-cosine method $[3,14,15]$ has been used to solve different types of nonlinear systems of PDEs.

In this paper, we applied the Tan-Cot method to solve the (2+1) - dimensional nonlinear Schrödinger equation, Gardner equation, modified KdV equation, perturbed Burgers equation, general Burger's-Fisher equation, and Benjamin-BonaMahony equation given respectively by:

$$
\begin{gather*}
i q_{t}+a q_{x x}-b q_{y y}+c|q|^{2} q=0  \tag{1}\\
u_{t}-6\left(u+\varepsilon^{2} u^{2}\right) u_{x}+u_{x x x}=0  \tag{2}\\
u_{t}-\delta u^{2} u_{x}+u_{x x x}=0  \tag{3}\\
u_{t}+a u u_{x}+b u_{x x}=c u^{2} u_{x}+\beta u u_{x x}+\gamma\left(u_{x}\right)^{2}+\delta u_{x x x}  \tag{4}\\
u_{t}-a u^{n} u_{x}+b u_{x x}+c u\left(1-u^{n}\right)=0  \tag{5}\\
u_{t}-u_{x x t}+u_{x}+u u_{x}=0 \tag{6}
\end{gather*}
$$

## 2. THE TAN-COT FUNCTION METHOD

Consider the nonlinear partial differential equation in the form

$$
\begin{equation*}
F\left(u, u_{t}, u_{x}, u_{y}, u_{t t}, u_{x x}, u_{x y}, u_{y y}, \ldots \ldots \ldots\right)=0 \tag{7}
\end{equation*}
$$

where $u(x, y, t)$ is a traveling wave solution of nonlinear partial differential equation Equation (7). We use the transformations,

$$
\begin{equation*}
u(x, y, t)=f(\xi) \tag{8}
\end{equation*}
$$

where $\xi=x+y-\lambda t$. This enables us to use the following changes:

$$
\begin{equation*}
\frac{\partial}{\partial t}(\cdot)=-\lambda \frac{d}{d \xi}(\cdot), \frac{\partial}{\partial x}(\cdot)=\frac{d}{d \xi}(\cdot), \frac{\partial}{\partial y}(\cdot)=\frac{d}{d \xi}(\cdot) \tag{9}
\end{equation*}
$$

Using Equation (9) to transfer the nonlinear partial differential equation Eq.(7) to nonlinear ordinary differential equation

$$
\begin{equation*}
Q\left(f, f^{\prime}, f^{\prime \prime}, f^{\prime \prime \prime}, \ldots\right)=0 \tag{10}
\end{equation*}
$$

The ordinary differential equation (10) is then integrated as long as all terms contain derivatives, where we neglect the integration constants. The solutions of many nonlinear equations can be expressed in the form:

$$
f(\xi)=\alpha \tan ^{\beta}(\mu \xi), \quad|\xi| \leq \frac{\pi}{2 \mu}
$$

or in the form

$$
\begin{equation*}
f(\xi)=\alpha \cot ^{\beta}(\mu \xi), \quad|\xi| \leq \frac{\pi}{2 \mu} \tag{11}
\end{equation*}
$$

where $\alpha, \mu$, and $\beta$ are parameters to be determined, $\mu$ and $c$ are the wave number and the wave speed, respectively. We use

$$
\begin{align*}
f(\xi) & =\alpha \tan ^{\beta}(\mu \xi) \\
f^{\prime} & =\alpha \beta \mu\left[\tan ^{\beta-1}(\mu \xi)+\tan ^{\beta+1}(\mu \xi)\right] \\
f^{\prime \prime} & =\alpha \beta \mu^{2}\left[(\beta-1) \tan ^{\beta-2}(\mu \xi)+2 \beta \tan ^{\beta}(\mu \xi)+(\beta+1) \tan ^{\beta+2}(\mu \xi)\right] \\
f^{\prime \prime \prime} & =\beta \mu^{3} \alpha\left[(\beta-1)(\beta-2) \tan ^{\beta-3}(\mu \xi)+\left(3 \beta^{2}-3 \beta+2\right) \tan ^{\beta-1}(\mu \xi)\right. \\
& \left.+(\beta+1)(\beta+2) \tan ^{\beta}(\mu \xi)+2 \beta^{2} \tan ^{\beta+1}(\mu \xi)+(\beta+1)(\beta+2) \tan ^{\beta+2}(\mu \xi)\right] \tag{12}
\end{align*}
$$

and their derivative. Or use

$$
\begin{align*}
f(\xi) & =\alpha \cot ^{\beta}(\mu \xi) \\
f^{\prime} & =-\alpha \beta \mu\left[\cot ^{\beta-1}(\mu \xi)+\cot ^{\beta+1}(\mu \xi)\right]  \tag{13}\\
f^{\prime \prime} & =\alpha \beta \mu^{2}\left[(\beta-1) \cot ^{\beta-2}(\mu \xi)+2 \beta \cot ^{\beta}(\mu \xi)+(\beta+1) \cot ^{\beta+2}(\mu \xi)\right]
\end{align*}
$$

and so on. We substitute (12) or (13) into the reduced equation (10), balance the terms of the tan functions when (12) are used, or balance the terms of the cot functions when (13) are used, and solve the resulting system of algebraic equations by using computerized symbolic packages. We next collect all terms with the same power in $\tan ^{k}(\mu \xi)$ or $\cot ^{k}(\mu \xi)$ and set to zero their coefficients to get a system of algebraic equations among the unknown's $\alpha, \mu$ and $\beta$, and solve the subsequent system.

## 3. APPLICATIONS

### 3.1. Schrödinger Equation

Let us first consider the (2+1) - dimensional nonlinear Schrödinger equation (16) that reads:

$$
\begin{equation*}
i q_{t}+a q_{x x}-b q_{y y}+c|q|^{2} q=0 \tag{14}
\end{equation*}
$$

where $a, b$ and $c$ are nonzero constants. Firstly, we introduce the transformations

$$
\begin{equation*}
q(x, y, t)=e^{(i \theta)} \cdot u(\xi), \quad \theta=\alpha x+\omega y+\delta t, \quad \xi=k(x+l y-\lambda t) \tag{15}
\end{equation*}
$$

where $\alpha, \omega, \delta, k, l$ and $\lambda$ are real constants. Substituting Equation (15) into Equation (14), we obtain the $\lambda=2(a \alpha-b \omega l)$ and $u(\xi)$ satisfy into the ODE:

$$
\begin{equation*}
-\left(\delta+a \alpha^{2}-b \omega^{2}\right) u(\xi)+\left(a-b l^{2}\right) k^{2} u^{\prime \prime}(\xi)+c(u(\xi))^{3}=0 \tag{16}
\end{equation*}
$$

Rewrite this second-order ordinary differential equation as follows:

$$
\begin{equation*}
u^{\prime \prime}+k_{1} u^{3}-k_{2} u=0 \tag{17}
\end{equation*}
$$

Where

$$
\begin{equation*}
k_{1}=\frac{c}{\left(a-b l^{2}\right) k^{2}}, \quad k_{2}=\frac{\delta+a \alpha^{2}-b \omega^{2}}{\left(a-b l^{2}\right) k^{2}} \tag{18}
\end{equation*}
$$

Seeking solutions of the form (12) we get:

$$
\begin{align*}
& \alpha \beta \mu^{2}\left[(\beta-1) \tan ^{\beta-2}(\mu \xi)+2 \beta \tan ^{\beta}(\mu \xi)+(\beta+1) \tan ^{\beta+2}(\mu \xi)\right] \\
+ & k_{1} \alpha^{3} \tan ^{3 \beta}(\mu \xi)-k_{2} \alpha \tan ^{\beta}(\mu \xi)=0 \tag{19}
\end{align*}
$$

Equating the exponents and the coefficients of each pair of the tan functions we find the following algebraic system:

$$
\begin{align*}
& \beta+2=3 \beta \text { then } \beta=1 \\
& \alpha \beta \mu^{2}(\beta+1)+k_{1} \alpha^{3}=0  \tag{20}\\
& 2 \alpha \beta^{2} \mu^{2}-k_{2} \alpha=0
\end{align*}
$$

By solving the algebraic system (20), we get

$$
\begin{equation*}
\alpha=\mp i \sqrt{\frac{\delta+a \alpha^{2}-b \omega^{2}}{c}}, \quad \mu=\mp \sqrt{\frac{\delta+a \alpha^{2}-b \omega^{2}}{2\left(a-b l^{2}\right) k^{2}}} \tag{21}
\end{equation*}
$$

Then by substituting Equation (21) into Equation (12) then, the exact soliton solution of equation (14) can be written in the form:

$$
\begin{equation*}
u(\xi)=\mp i \sqrt{\frac{\delta+a \alpha^{2}-b \omega^{2}}{c}} \tan \left(\mp \sqrt{\frac{\delta+a \alpha^{2}-b \omega^{2}}{2\left(a-b l^{2}\right)}}(x+l y-\lambda t)\right) \tag{22}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
q(x, y, t)=\mp i \sqrt{\frac{\delta+a \alpha^{2}-b \omega^{2}}{c}} \tan \left(\mp \sqrt{\frac{\delta+a \alpha^{2}-b \omega^{2}}{2\left(a-b l^{2}\right)}}(x+l y-\lambda t)\right) e^{i(\alpha x+\omega y+\delta t)} \tag{23}
\end{equation*}
$$

for $\alpha=\omega=\delta=k=l=1, a \neq b, a=c=1, b=.5$ and (23) becomes:

$$
\begin{equation*}
q(x, y, t)=\mp i \sqrt{\frac{3}{2}} \tan \left(\mp \sqrt{\frac{3}{2}}(x+y-t)\right) e^{i(x+y+t)} \tag{24}
\end{equation*}
$$

### 3.2. Gardner Equation

Consider the Gardner equation [17,18]

$$
\begin{equation*}
u_{t}-6\left(u+\varepsilon^{2} u^{2}\right) u_{x}+u_{x x x}=0 \tag{25}
\end{equation*}
$$

This equation known as the mixed $\mathrm{KdV}-\mathrm{mKdV}$ equation is very widely studied in various areas of Physics that includes Plasma Physics, Fluid Dynamics, Quantum Field Theory, Solid State Physics and others [18].

We introduce the transformation $\xi=k(x-\lambda t)$, where $k$, and $\lambda$ are real constants. Equation (25) transforms to the ODE:

$$
\begin{equation*}
-k \lambda u^{\prime}-3 k\left(u^{2}\right)^{\prime}-2 \varepsilon^{2} k\left(u^{3}\right)^{\prime}+k^{3} u^{\prime \prime \prime}=0 \tag{26}
\end{equation*}
$$

Integrating (26) once with zero constant to get the following ordinary differential equation:

$$
\begin{equation*}
\lambda u+3 u^{2}+2 \varepsilon^{2} u^{3}-k^{2} u^{\prime \prime}=0 \tag{27}
\end{equation*}
$$

Seeking the solution in (13)

$$
\begin{align*}
& \quad \lambda \alpha \cot ^{\beta}(\mu \xi)+3 \alpha^{2} \cot ^{2 \beta}(\mu \xi)+2 \varepsilon^{2} \alpha^{3} \cot ^{3 \beta}(\mu \xi) \\
& -  \tag{28}\\
& -\alpha \beta \mu^{2} k^{2}\left[(\beta-1) \cot ^{\beta-2}(\mu \xi)+2 \beta \cot ^{\beta}(\mu \xi)+(\beta+1) \cot ^{\beta+2}(\mu \xi)\right]=0
\end{align*}
$$

Equating the exponents and the coefficients of each pair of the cot functions we find the following algebraic system:

$$
\begin{equation*}
3 \beta=\beta-2 \rightarrow \beta=-1 \tag{29}
\end{equation*}
$$

Substituting Equation (29) into Equation (28) to get:

$$
\begin{gather*}
\lambda \alpha \cot ^{-1}(\mu \xi)+3 \alpha^{2} \cot ^{-2}(\mu \xi)+2 \varepsilon^{2} \alpha^{3} \cot ^{-3}(\mu \xi)  \tag{30}\\
-\alpha \beta \mu^{2} k^{2}\left[(\beta-1) \cot ^{-3}(\mu \xi)+2 \beta \cot ^{-1}(\mu \xi)\right]=0
\end{gather*}
$$

Equating the exponents and the coefficients of each pair of the cot function, we obtain a system of algebraic equations:

$$
\begin{align*}
\cot ^{-3}(\mu \xi) & : 2 \varepsilon^{2} \alpha^{3}-2 \alpha \mu^{2} k^{2}=0 \\
\cot ^{-2}(\mu \xi) & : 3 \alpha^{2}=0  \tag{31}\\
\cot ^{-1}(\mu \xi) & : \lambda \alpha-2 \alpha \mu^{2} k^{2}=0
\end{align*}
$$

By solving the algebraic system (31), we get,

$$
\begin{equation*}
\lambda=2 \mu^{2} k^{2}, \quad \alpha=\mp \frac{k \mu}{\varepsilon} \tag{32}
\end{equation*}
$$

Then by substituting Equation (32) into Equation (12), the exact soliton solution of equation (27) can be written in the form

$$
\begin{equation*}
u(x, t)=\mp \frac{k \mu}{\varepsilon} \tan \left(\mu k\left(x-2 \mu^{2} k^{2} t\right)\right), \quad 0<\mu k\left(x-2 \mu^{2} k^{2} t\right)<\pi \tag{33}
\end{equation*}
$$

For $\mu=k=\varepsilon=1$, then (33) becomes:

$$
\begin{equation*}
u(x, t)=\tan (x-2 t) \tag{34}
\end{equation*}
$$

$u(x, t)$ in (34) is represented in Figure 1 for $-10 \leq x \leq 10$ and $0 \leq t \leq 1$.

### 3.3. Dispersive Equation

Consider the ( $1+1$ ) - dimensional nonlinear dispersive equation

$$
\begin{equation*}
u_{t}-\delta u^{2} u_{x}+u_{x x x}=0 \tag{35}
\end{equation*}
$$

where $\delta$ is a nonzero positive constant. This equation is called the modified KdV equation [19], which arises in the process of understanding the role of nonlinear dispersion and in the formation of structures like liquid drops, and it exhibits


Figure 1
Represents $u(x, t)$ in (34) for $-10 \leq x \leq 10$ and $0 \leq t \leq 1$
compaction solitons with compact support. To find the traveling wave solutions of Equation (29), [19] used $G^{\prime} / G$ expansion Method.

Let us now solve Equation (35) by the proposed method. We introduce the transformation $\xi=k(x-\lambda t)$, where $k$ and $\lambda$ are real constants. Equation (35) transforms to the ODE:

$$
\begin{equation*}
-k \lambda u^{\prime}-\frac{\delta}{3} k\left(u^{3}\right)^{\prime}+k^{3} u^{\prime \prime \prime}=0 \tag{36}
\end{equation*}
$$

Integrating (36) once with zero constant to get the following ordinary differential equation:

$$
\begin{equation*}
\lambda u+\frac{\delta}{3} u^{3}-k^{2} u^{\prime \prime}=0 \tag{37}
\end{equation*}
$$

Seeking the solution in (13)

$$
\begin{align*}
& \lambda \alpha \cot ^{\beta}(\mu \xi)+\frac{\delta}{3} \alpha^{3} \cot ^{3 \beta}(\mu \xi)  \tag{38}\\
- & \alpha \beta \mu^{2} k^{2}\left[(\beta-1) \cot ^{\beta-2}(\mu \xi)+2 \beta \cot ^{\beta}(\mu \xi)+(\beta+1) \cot ^{\beta+2}(\mu \xi)\right]=0
\end{align*}
$$

Equating the exponents and the coefficients of each pair of the cot functions we find the following algebraic system: $3 \beta=\beta+2 \rightarrow \beta=1$

$$
\begin{array}{ll}
\cot ^{3}(\mu \xi): & \frac{\delta}{3} \alpha^{3}-\alpha \beta \mu^{2} k^{2}(\beta+1)=0  \tag{39}\\
\cot ^{1}(\mu \xi): & \lambda \alpha-\alpha \beta^{2} \mu^{2} k^{2}=0
\end{array}
$$

By solving the algebraic system (39), we get

$$
\begin{equation*}
\lambda=\mu^{2} k^{2}, \quad \alpha=\mp \sqrt{\frac{6}{\delta}} k \mu \tag{40}
\end{equation*}
$$

Then by substituting Equation (40) into Equation (13), the exact soliton solution of Equation (35) can be written in the form

$$
\begin{equation*}
u(x, t)=\mp \sqrt{\frac{6}{\delta}} k \mu \cot \left(\mu k\left(x-\mu^{2} k^{2} t\right)\right), \quad 0<\mu k\left(x-\mu^{2} k^{2} t\right)<\pi \tag{41}
\end{equation*}
$$

For $\mu=k=\delta=1$, Equation (41) becomes

$$
\begin{equation*}
u(x, t)=\mp \sqrt{6} \cot (x-t) \tag{42}
\end{equation*}
$$

$u(x, t)$ in (42) is represented in Figure 2 for $-10 \leq x \leq 10$ and $0 \leq t \leq 1$.


Figure 2
Represents $u(x, t)$ in (42) for $-10 \leq x \leq 10$ and $0 \leq t \leq 1$

### 3.4. Perturbed Burgers Equation

In this section the study is going to be focused on the perturbed Burgers equation. The solitary wave ansatz method will be adopted to obtain the exact 1 -soliton solution of the Burgers equation in $(1+1)$ dimensions. The search is going to be for a topological 1 -soliton solution. The perturbed Burgers equation that is given by the following form [20]:

$$
\begin{equation*}
u_{t}+a u u_{x}+b u_{x x}=c u^{2} u_{x}+\beta u u_{x x}+\gamma\left(u_{x}\right)^{2}+\delta u_{x x x} \tag{43}
\end{equation*}
$$

Equation (43) appears in the study of gas dynamics and also in free surface motion of waves in heated fluids. The perturbation terms are obtained from longwave perturbation theory. Equation (43) shows up in the long-wave small-amplitude limit of extended systems dominated by dissipation, where dispersion is also present at a higher order [20].

To solve Equation (43) by the proposed method. We introduce the transformation $\xi=k(x-\lambda t)$, where $k$, and $\lambda$ are real constants. Equation (43) transforms to the ODE:

$$
\begin{equation*}
-\left[\lambda-a u+c u^{2}\right] u^{\prime}+[b k-d k u] u^{\prime \prime}-\gamma k\left(u^{\prime}\right)^{2}-\delta k^{2} u^{\prime \prime \prime}=0 \tag{44}
\end{equation*}
$$

Seeking the solution in (12)

$$
\begin{align*}
& -\alpha \beta \mu\left[\lambda \tan ^{\beta-1}(\mu \xi)-a \alpha \tan ^{2 \beta-1}(\mu \xi)+c \alpha^{2} \tan ^{3 \beta-1}(\mu \xi)\right] \\
& -\alpha \beta \mu\left[\lambda-a \alpha \tan ^{2 \beta+1}(\mu \xi)+c \alpha^{2} \tan ^{3 \beta+1}(\mu \xi)\right] \\
& +\alpha \beta \mu^{2} b k\left[(\beta-1) \tan ^{\beta-2}(\mu \xi)+2 \beta \tan ^{\beta}(\mu \xi)+(\beta+1) \tan ^{\beta+2}(\mu \xi)\right] \\
& -\alpha \beta \mu^{2} d k a\left[(\beta-1) \tan ^{2 \beta-2}(\mu \xi)+2 \beta \tan ^{2 \beta}(\mu \xi)+(\beta+1) \tan ^{2 \beta+2}(\mu \xi)\right] \\
& -\gamma k \alpha^{2} \beta^{2} \mu^{2}\left[\tan ^{2 \beta-2}(\mu \xi)+2 \tan ^{2 \beta}(\mu \xi)+\tan ^{2 \beta+2}(\mu \xi)\right] \\
& -\delta k^{2} \beta \mu^{3} \alpha\left[(\beta-1)(\beta-2) \tan ^{\beta-3}(\mu \xi)+\left(3 \beta^{2}-3 \beta+2\right) \tan ^{\beta-1}(\mu \xi)\right. \\
& \left.+(\beta+1)(\beta+2) \tan ^{\beta}(\mu \xi)+2 \beta^{2} \tan ^{\beta+1}(\mu \xi)+(\beta+1)(\beta+2) \tan ^{\beta+2}(\mu \xi)\right]=0 \tag{45}
\end{align*}
$$

From (45), equating exponents $2 \beta-2$ and $3 \beta-1$ yield

$$
\begin{equation*}
2 \beta-2=3 \beta-1, \text { so that } \beta=-1 \tag{46}
\end{equation*}
$$

It needs to be noted that the same value of $\beta$ is obtained when the exponent pairs $\beta-2=2 \beta-1,2 \beta-2=\beta-3$ are equated, thus setting their coefficients to zero yields:

$$
\begin{align*}
& \lambda+c \alpha^{2}-2 \mu d k \alpha-2 \gamma \alpha k \mu+8 \delta k^{2} \mu^{2}=0 \\
& c \alpha^{2}-2 \mu d k \alpha-\gamma \alpha k \mu+6 \delta k^{2} \mu^{2}=0  \tag{47}\\
& -a \alpha+2 \mu b k=0 \\
& \lambda-\gamma \alpha k \mu=0
\end{align*}
$$

By solving the algebraic system (47), we get

$$
\begin{equation*}
\delta=\frac{b}{3 a^{2}}[2 d a-2 c b+\gamma a], \alpha=\frac{2 \mu b k}{a}, \lambda=2 \underset{a}{a} \gamma k^{2} \mu^{2} \tag{48}
\end{equation*}
$$

Then by substituting Equation (48) into Equation (12), the exact soliton solution of equation (43) can be written in the form

$$
\begin{equation*}
u(x, t)=\frac{2 b k}{a} \mu \cot \left[\mu k\left(x-2 \frac{b}{a} \gamma k^{2} \mu^{2} t\right)\right] \tag{49}
\end{equation*}
$$

for $\mu=k=a=b=1, \gamma=-1$

$$
\begin{equation*}
u(x, t)=2 \cot (x+2 t) \tag{50}
\end{equation*}
$$

Figure 3 represents $u(x, t)$ in (50) for $-10 \leq x \leq 10$ and $0.1 \leq t \leq 1$.

### 3.5. The General Burgers-Fisher Equation

Consider the following general Burger's-Fisher equation [21]

$$
\begin{equation*}
u_{t}-a u^{n} u_{x}+b u_{x x}+c u\left(1-u^{n}\right)=0 \tag{51}
\end{equation*}
$$

where $a, b$ and $c$ are nonzero constants. We introduce the transformation $\xi=$ $k(x-\lambda t)$, where $k$, and $\lambda$ are real constants. The traveling wave variable $\xi$ permits us converting Equation (51) into the following ODE:

$$
\begin{equation*}
-\lambda k u^{\prime}+a k u^{n} u^{\prime}+b k^{2} u^{\prime \prime}+c u-c u^{n+1}=0 \tag{52}
\end{equation*}
$$



Figure 3
Represents $u(x, t)$ in (50) for $-10 \leq x \leq 10$ and $0.1 \leq t \leq 1$

Seeking the solution in (12)

$$
\begin{align*}
& -\lambda k \alpha \beta \mu\left[\tan ^{\beta-1}(\mu \xi)+\tan ^{\beta+1}(\mu \xi)\right] \\
& +a k \alpha^{n+1} \beta \mu\left[\tan ^{(n+1) \beta-1}(\mu \xi)+\tan ^{(n+1) \beta+1}(\mu \xi)\right]  \tag{53}\\
& +b k^{2} \alpha \beta \mu^{2}\left[(\beta-1) \tan ^{\beta-1}(\mu \xi)+2 \beta \tan ^{\beta}(\mu \xi)+(\beta+1) \tan ^{\beta+2}(\mu \xi)\right] \\
& +c \alpha \tan ^{\beta}(\mu \xi)-c \alpha^{n+1} \tan ^{(n+1) \beta}(\mu \xi)=0
\end{align*}
$$

From (53), equating exponents $(n+1) \beta+1$ and $\beta+2$ yield

$$
\begin{equation*}
(n+1) \beta+1=\beta+2 \tag{54}
\end{equation*}
$$

so that

$$
\begin{equation*}
\beta=\frac{1}{n} \tag{55}
\end{equation*}
$$

Equating exponents $\beta+1$ and $(n+1) \beta$ and the pairs $(n+1) \beta-1$ and $\beta$ gives the same value of $\beta$ in (55), so that substitute (55) in (53) then

$$
\begin{align*}
& -\lambda k \alpha \beta \mu\left[\tan ^{\frac{1}{n}-1}(\mu \xi)+\tan ^{\frac{1}{n}+1}(\mu \xi)\right] \\
& +a k \alpha^{n+1} \beta \mu\left[\tan ^{\frac{1}{n}}(\mu \xi)+\tan ^{\frac{1}{n}+2}(\mu \xi)\right]  \tag{56}\\
& +b k^{2} \alpha \beta \mu^{2}\left[(\beta-1) \tan ^{\frac{1}{n}-2}(\mu \xi)+2 \beta \tan ^{\frac{1}{n}}(\mu \xi)+(\beta+1) \tan ^{\frac{1}{n}+2}(\mu \xi)\right] \\
& +c \alpha \tan ^{\frac{1}{n}}(\mu \xi)-c \alpha^{n+1} \tan ^{\frac{1}{n}+1}(\mu \xi)=0
\end{align*}
$$

Thus setting the coefficients of the same pairs to zero yields:

$$
\begin{align*}
& c \alpha^{n+1}+\lambda k \alpha \beta \mu=0 \\
& 2 b k^{2} \alpha \beta^{2} \mu^{2}+a k \alpha^{n+1} \beta \mu+c \alpha=0  \tag{57}\\
& b k^{2} \alpha \beta(\beta+1) \mu^{2}+a k \alpha^{n+1} \beta \mu=0
\end{align*}
$$

By solving the algebraic system (57), we get

$$
\begin{equation*}
\lambda=\frac{b^{2} k^{2} \mu^{2}}{a n^{2}}\left(n^{2}-1\right), \quad c=\frac{b \mu^{2} k^{2}}{n^{2}}(n-1), \quad \alpha=\left(-\frac{b k(n+1) \mu}{a n}\right)^{\frac{1}{n}} \tag{58}
\end{equation*}
$$

Then by substituting (58) into Equation (12), the exact soliton solution of Equation (51) can be written in the form

$$
\begin{equation*}
u(x, t)=\left[-\frac{b k(n+1) \mu}{a n} \tan \left\{\mu k\left(x-\frac{b^{2} k^{2} \mu^{2}}{a n^{2}}\left(n^{2}-1\right) t\right)\right\}\right]^{\frac{1}{n}} \tag{59}
\end{equation*}
$$

It is worth noting that the proposed Tan-Cot function method is applicable here if $n$ does not equal to 1 .

### 3.6. Benjamin-Bona-Mahony (BBM) Equation

Consider the BBM equation [22]

$$
\begin{equation*}
u_{t}-u_{x x t}+u_{x}+u u_{x}=0 \tag{60}
\end{equation*}
$$

We introduce the transformation $\xi=k(x-\lambda t)$, where $k$, and $\lambda$ are real constants. The traveling wave variable $\xi$ permits us converting Equation (60) into the following ODE:

$$
\begin{equation*}
k^{2} \lambda u^{\prime \prime \prime}+[1+u-\lambda] u^{\prime}=0 \tag{61}
\end{equation*}
$$

Seeking the solution in (12)

$$
\begin{align*}
& k^{2} \lambda \beta \mu^{3} \alpha\left[(\beta-1)(\beta-2) \tan ^{\beta-3}(\mu \xi)+\left(3 \beta^{2}-3 \beta+2\right) \tan ^{\beta-1}(\mu \xi)\right. \\
& \left.+(\beta+1)(\beta+2) \tan ^{\beta}(\mu \xi)+2 \beta^{2} \tan ^{\beta+1}(\mu \xi)+(\beta+1)(\beta+2) \tan ^{\beta+2}(\mu \xi)\right] \\
& +\alpha \beta \mu(1-\lambda)\left\{\tan ^{\beta-1}(\mu \xi)+\tan ^{\beta+1}(\mu \xi)\right\}+\alpha^{2} \beta \mu\left\{\tan ^{2 \beta-1}(\mu \xi)+\tan ^{2 \beta+1}(\mu \xi)\right\}=0 \tag{62}
\end{align*}
$$

From Equation (62), equating exponents $\beta-3$ and $2 \beta-1$ yield

$$
\begin{equation*}
\beta-3=2 \beta-1 \tag{63}
\end{equation*}
$$

so that

$$
\begin{equation*}
\beta=-2 \tag{64}
\end{equation*}
$$

equating exponents of the pairs $\beta-1$ and $2 \beta+1$ gives the same value of $\beta$ in (58), so that substitute (64) in (62) then setting coefficients of the same pairs in (62) to zero yields:

$$
\begin{align*}
& k^{2} \lambda \mu^{2}(\beta-1)(\beta-2)+\alpha=0 \\
& k^{2} \lambda \mu^{2}\left(3 \beta^{2}-3 \beta+2\right)+1-\lambda+\alpha=0  \tag{65}\\
& 2 \beta^{2} k^{2} \lambda \mu^{2}+1-\lambda=0
\end{align*}
$$

By solving the algebraic system (65), we get

$$
\begin{equation*}
\alpha=-\frac{12 k^{2} \mu^{2}}{1-8 k^{2} \mu^{2}}, \quad \lambda=\frac{1}{1-8 k^{2} \mu^{2}} \tag{66}
\end{equation*}
$$

Then by substituting Equation (66) into Equation (12), the exact soliton solution of equation (60) can be written in the form

$$
\begin{equation*}
u(x, t)=-\frac{12 k^{2} \mu^{2}}{1-8 k^{2} \mu^{2}} \cot ^{2}\left[\mu k\left(x-\frac{1}{1-8 k^{2} \mu^{2}} t\right)\right] \tag{67}
\end{equation*}
$$

For $k=\mu=1$, Equation (67) becomes:

$$
\begin{equation*}
u(x, t)=\frac{12}{7} \cot ^{2}\left(x+\frac{1}{7} t\right) \tag{68}
\end{equation*}
$$

$u(x, t)$ in $(68)$ is represented in Figure 4 for $-4 \leq x \leq 4$ and $0.1 \leq t \leq 1$.


Figure 4
Represents $u(x, t)$ in (68) for $-4 \leq x \leq 4$ and $0.1 \leq t \leq 1$

## 4. CONCLUSION

In this paper, new method called the Tan-Cot function method has been successfully implemented to establish new solitary wave solutions for various types of nonlinear PDEs. We can say that the new method can be extended to solve the problems of nonlinear partial differential equations which arising in the theory of solitons and other areas [23-29].

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